



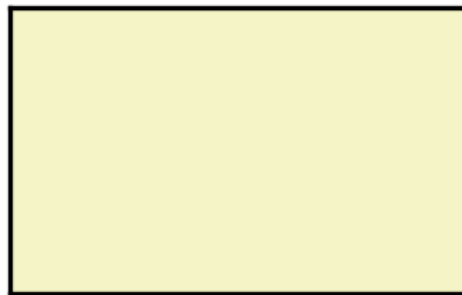
New insights on NO_x sources from the divergence of the mean NO_2 flux

Steffen Beirle, Christian Borger, Steffen Dörner,
Vinod Kumar, Thomas Wagner

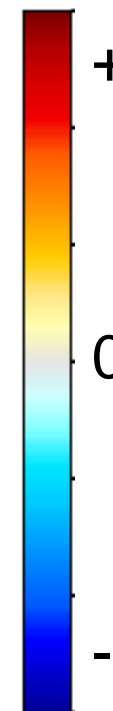
*Synthetic data
for illustration:*

E: Emissions

E



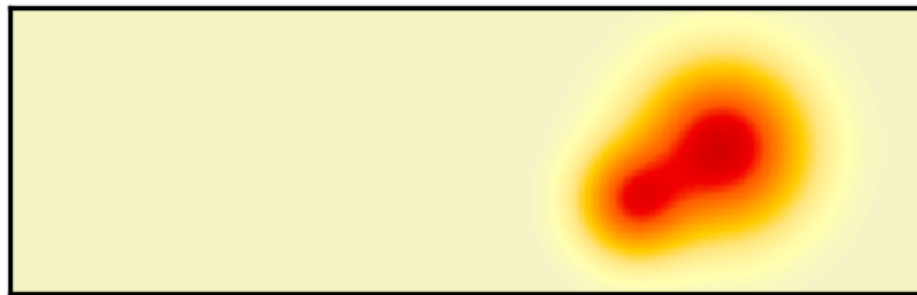
Created by Symbolon
from Noun Project



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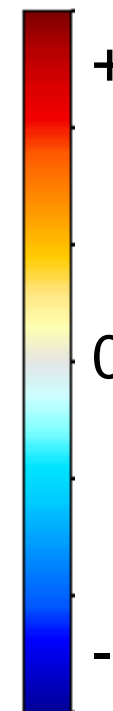
E



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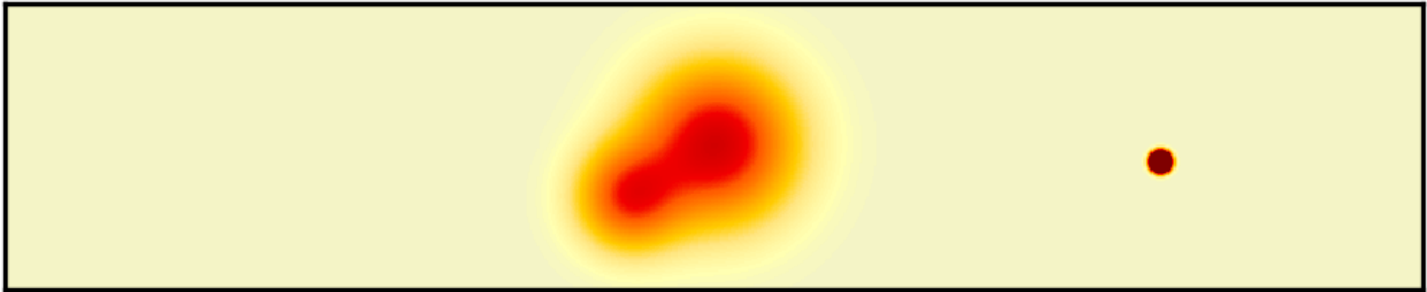
Created by Bianca Bezeready
from Noun Project



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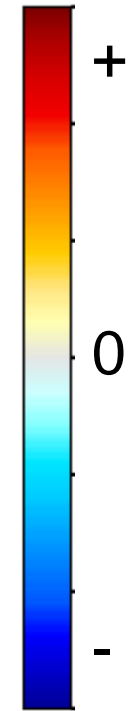
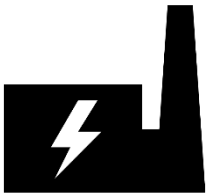
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Created by Bianca Bezereby
from Noun Project

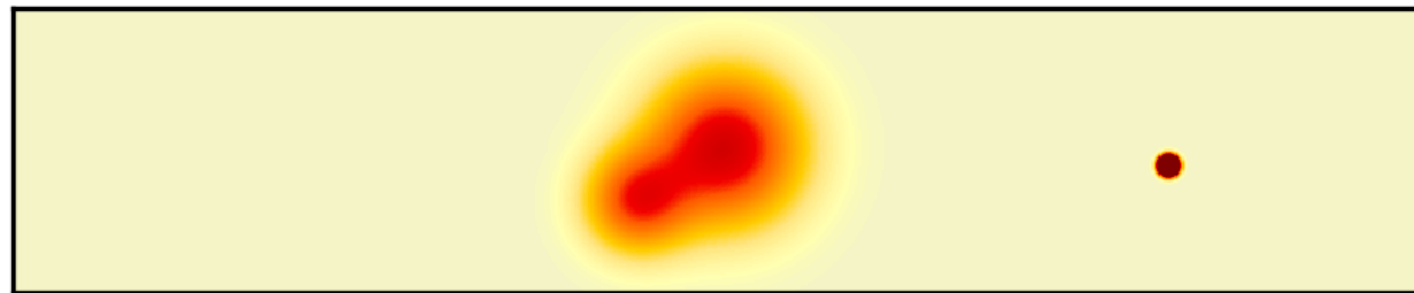


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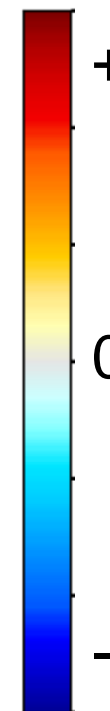
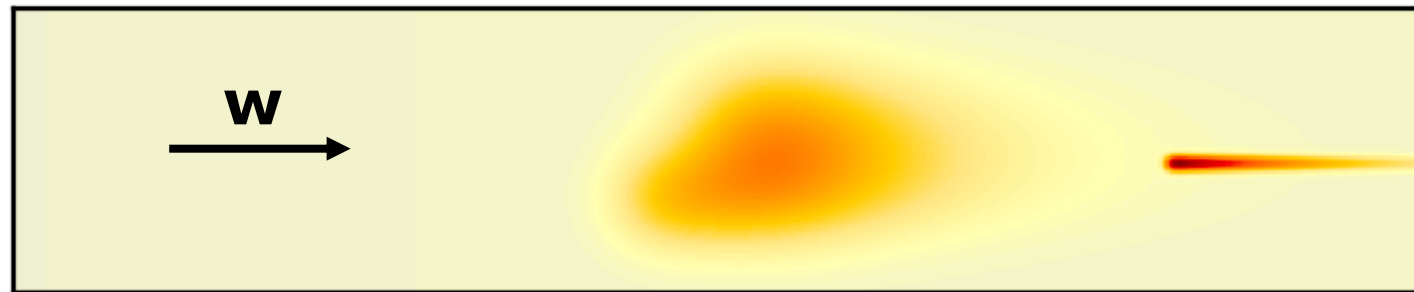


V: Vertical column

$\mathbf{w}=(u, v)$: Wind

$\mathbf{F} = \mathbf{w} \cdot \mathbf{V}$: Flux

V



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for illustration:*

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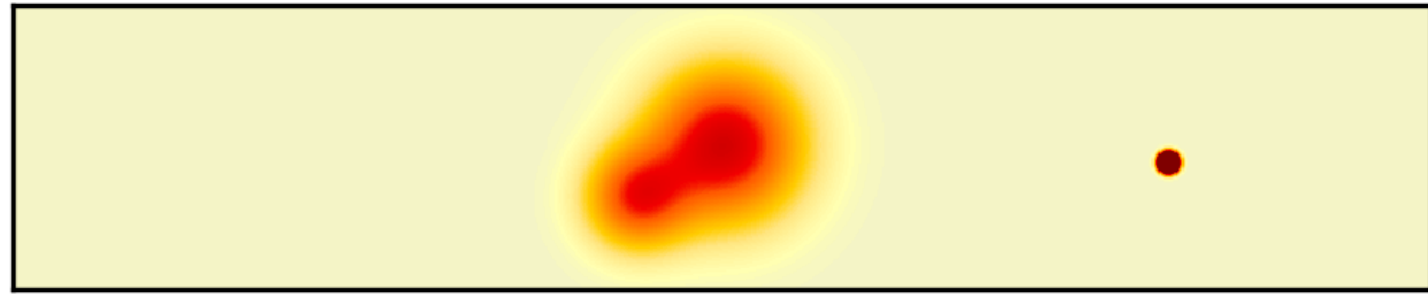
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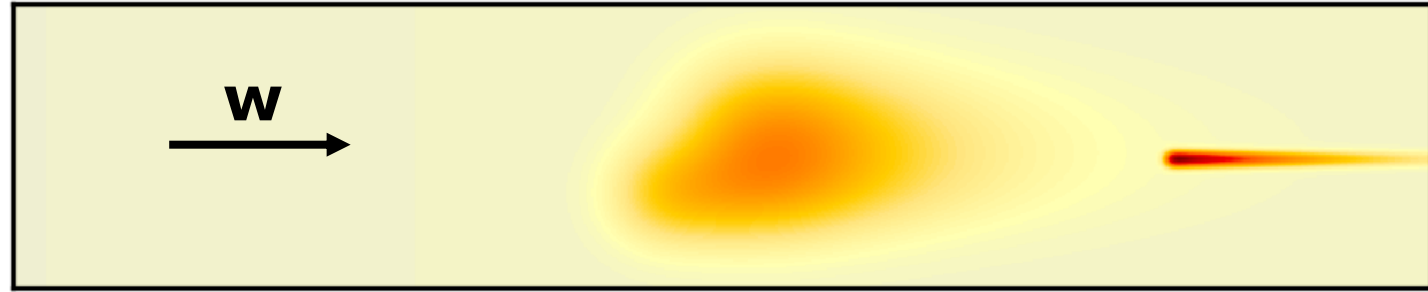
$\mathbf{F} = \mathbf{w} \cdot \mathbf{V}$: Flux

$D = \nabla \cdot \mathbf{F}$:
Divergence

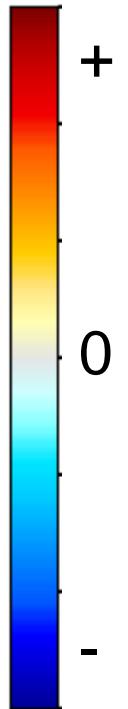
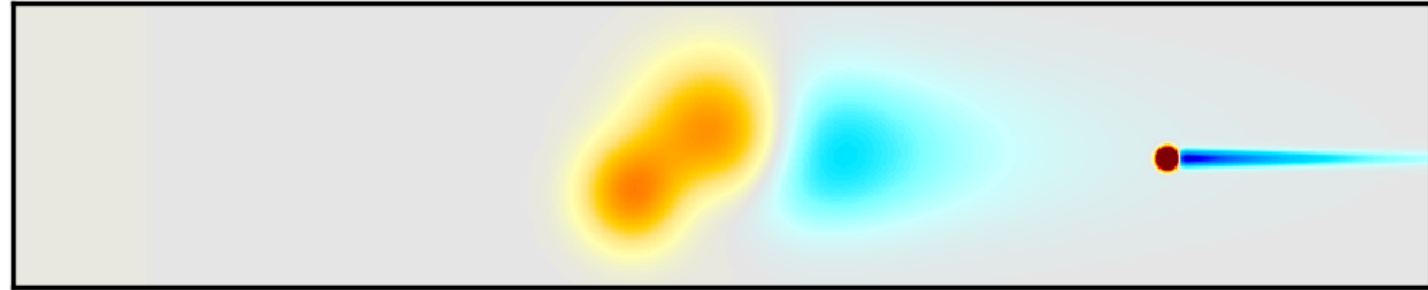
E



V



D

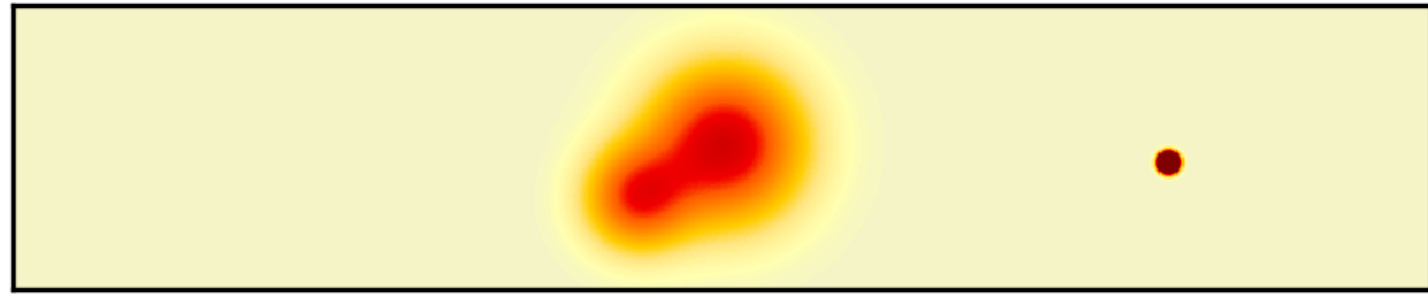


*Synthetic data
for illustration:*



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E

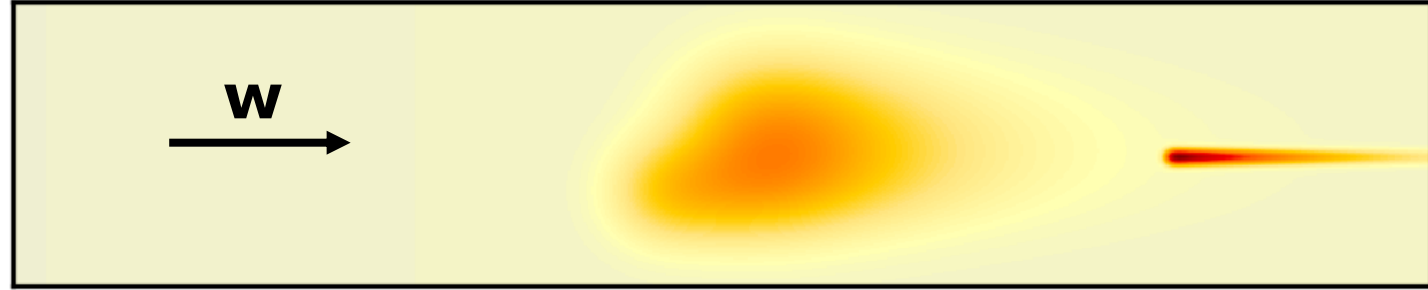


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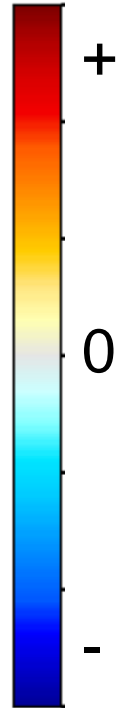
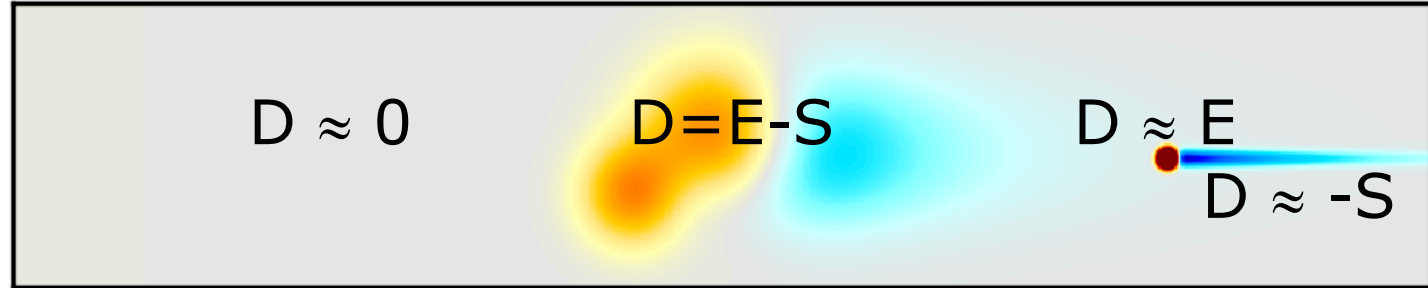
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V



$D = \nabla \cdot \mathbf{F}$:
Divergence

D



Steady state:

$$D = E - S$$

S: Sinks

$$S = V/\tau$$

$$E = D + S$$

*Synthetic data
for illustration:*

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Steady state:

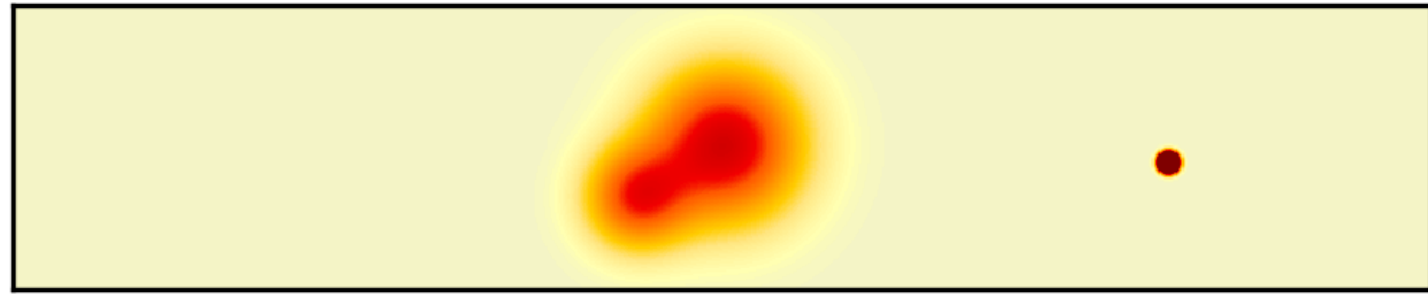
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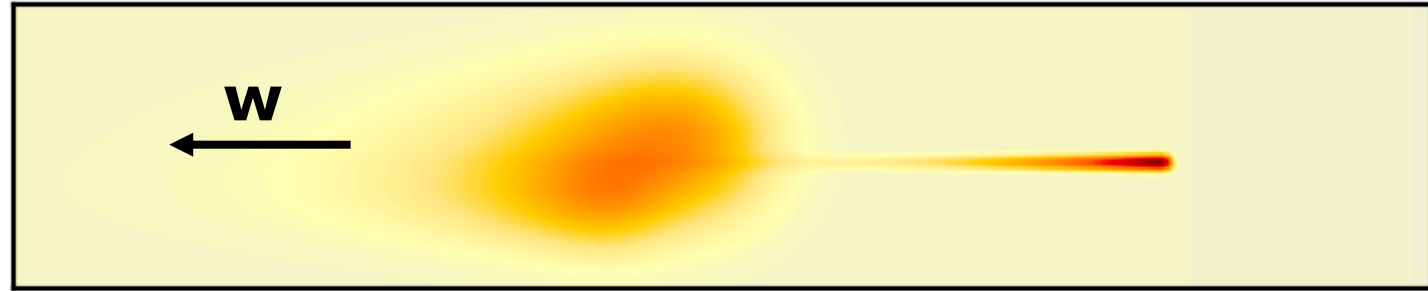
$$S = V/\tau$$

$$E = D + S$$

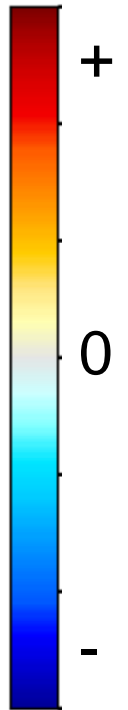
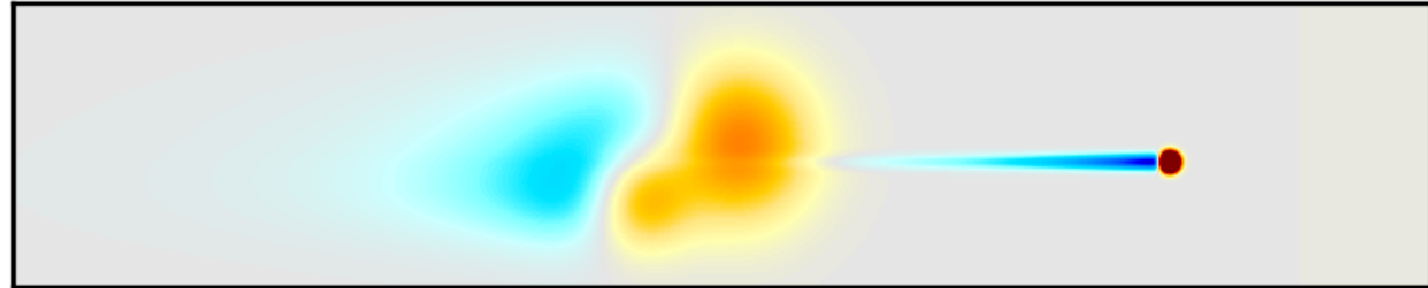
E



V



D



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Steady state:

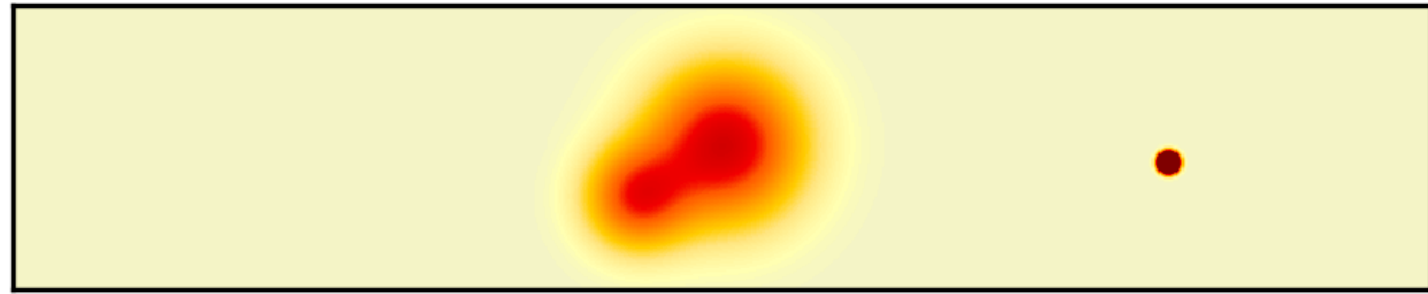
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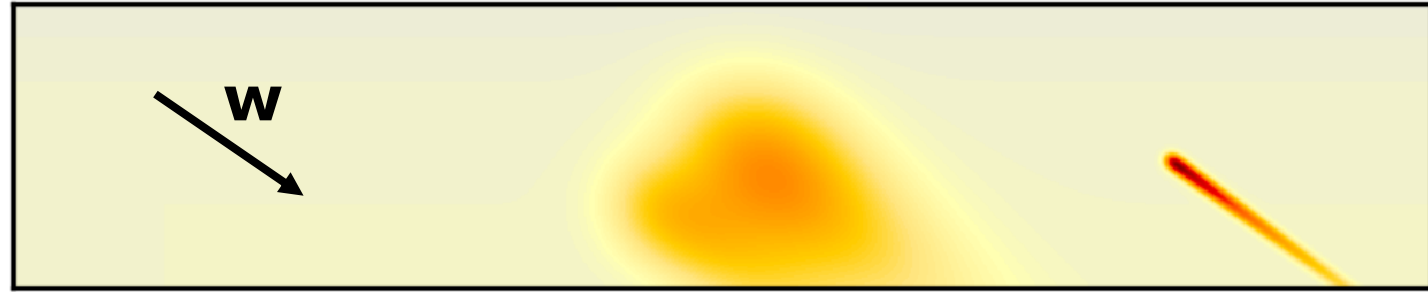
$$S = V/\tau$$

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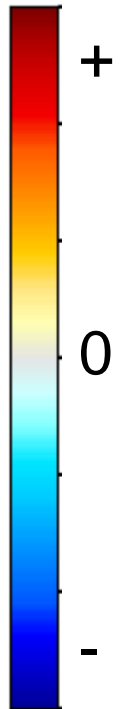
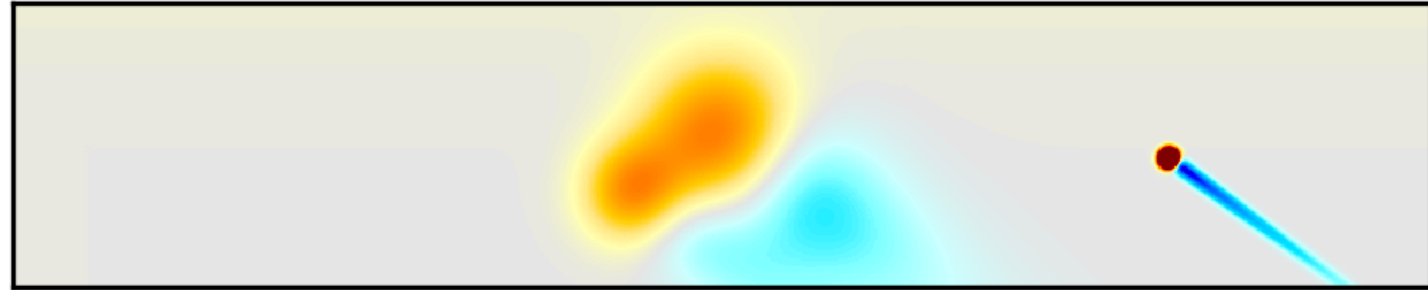
E



V



D



Synthetic data for illustration:

E: Emissions

V: Vertical column

$\mathbf{w} = (u, v)$: Wind

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Steady state:

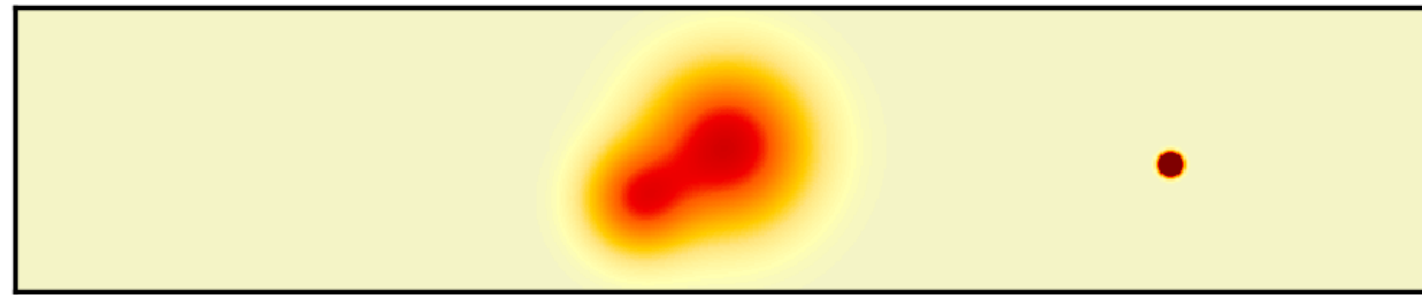
$$D = E - S$$

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$$S = V/\tau$$

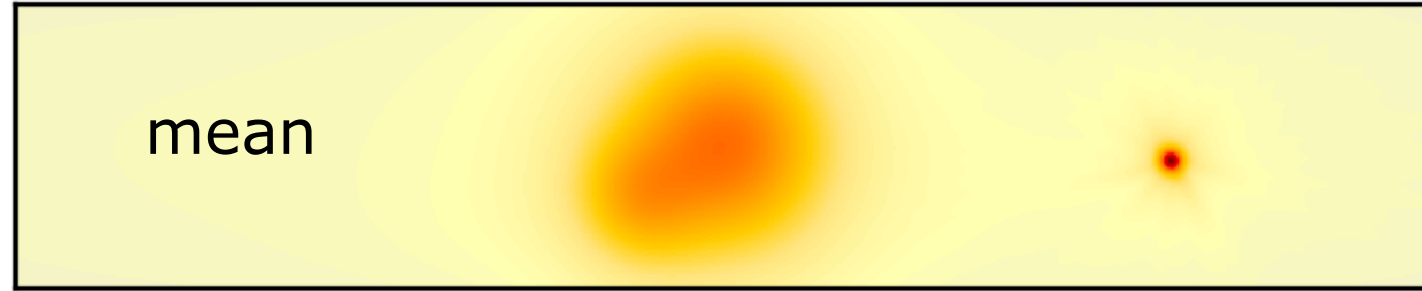
$$E = D + S$$

E



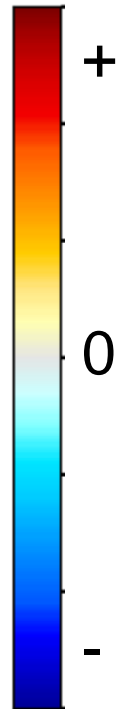
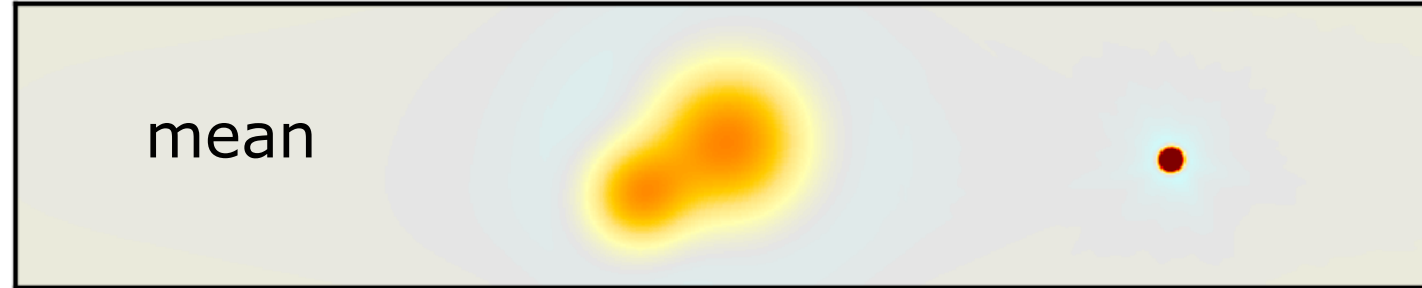
V

mean



D

mean



Reality is more complex:

- Turbulence & diffusion
- τ might change with downwind distance
- 3rd dimension: \mathbf{w} and τ change with altitude
- No steady state: \mathbf{w} , E , τ ... change with time

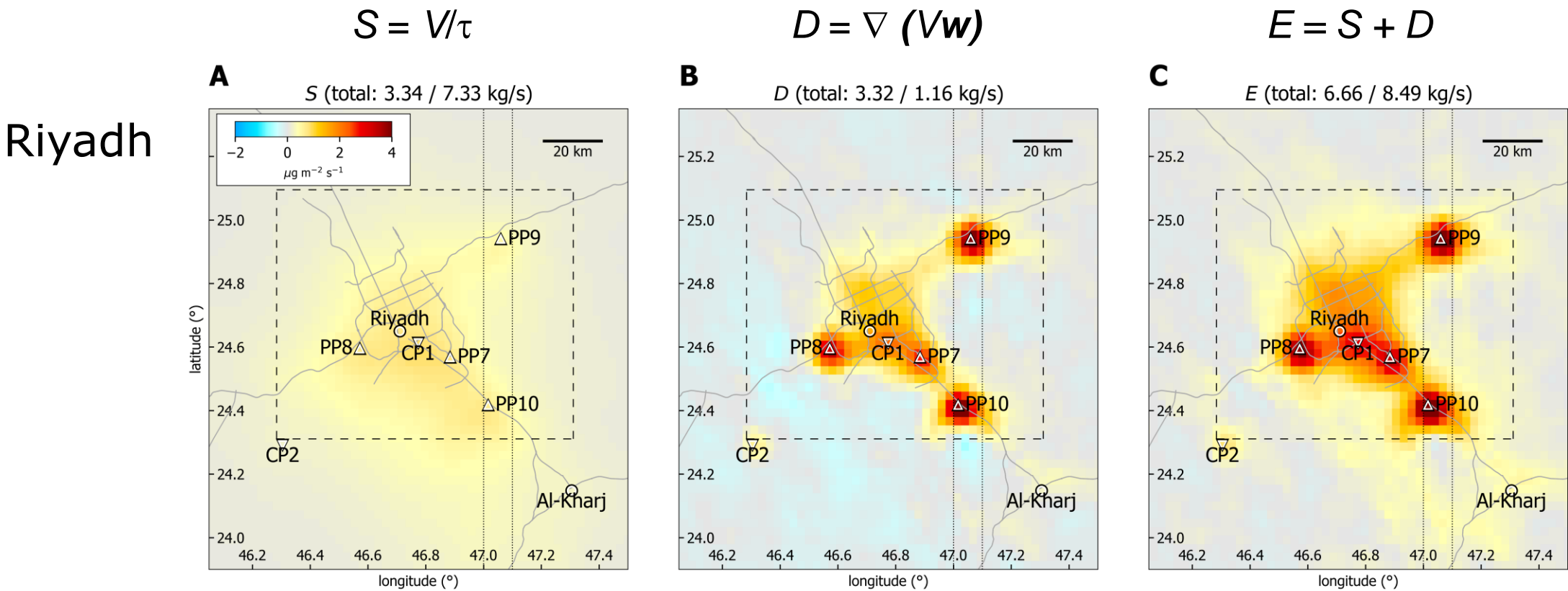
Not critical for point sources!

ATMOSPHERIC SCIENCE

Pinpointing nitrogen oxide emissions from space

Steffen Beirle^{1*}, Christian Borger¹, Steffen Dörner¹, Ang Li², Zhaokun Hu², Fei Liu^{3,4}, Yang Wang¹, Thomas Wagner^{1,5}

Beirle *et al.*, *Sci. Adv.* 2019;**5**:eaax9800 13 November 2019



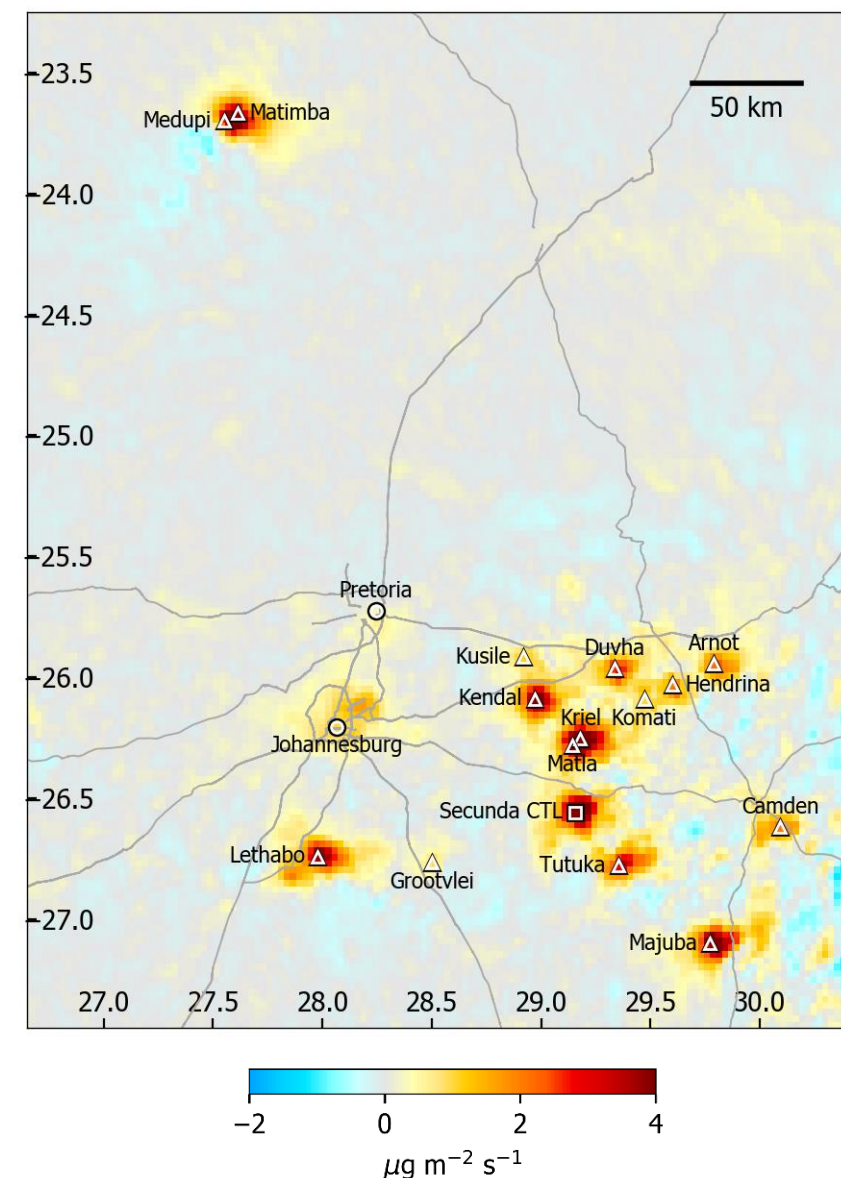


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Highveld,
South Africa



Catalog of NO_x emissions from point sources as derived from the divergence of the NO₂ flux for TROPOMI

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Steffen Beirle¹, Christian Borger¹, Steffen Dörner¹, Henk Eskes², Vinod Kumar¹, Adrianus de Laat²,
and Thomas Wagner¹

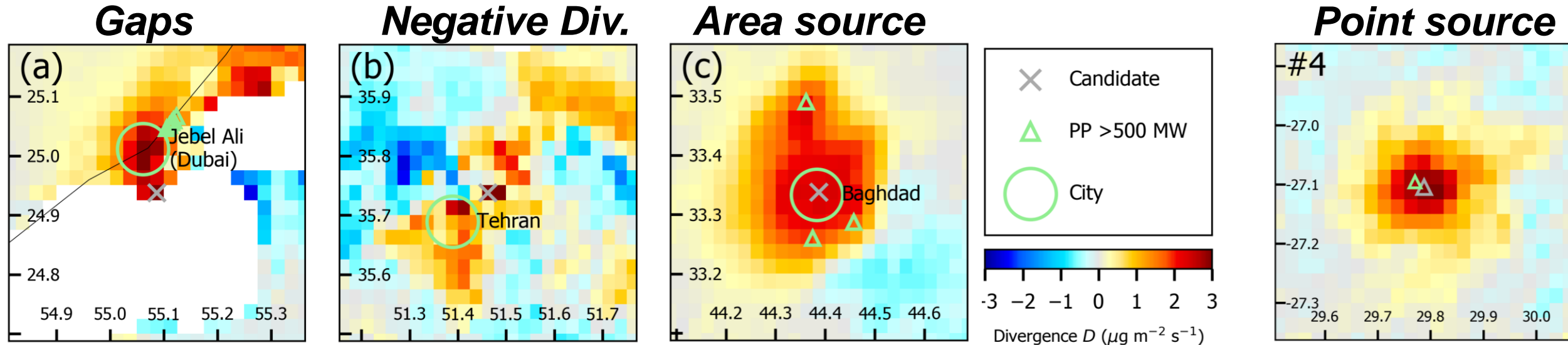
<https://doi.org/10.5194/essd-13-2995-2021>

- 451 point sources detected
(power plants, cement plants, metal smelters, industrial areas, small cities)
- For 242 point sources:
match in Global Power Plant Database within 5 km
- Below:
 - method (short)
 - results (short)
 - limitations & potential improvements

Method: Iterative peak fitting (fully automated)

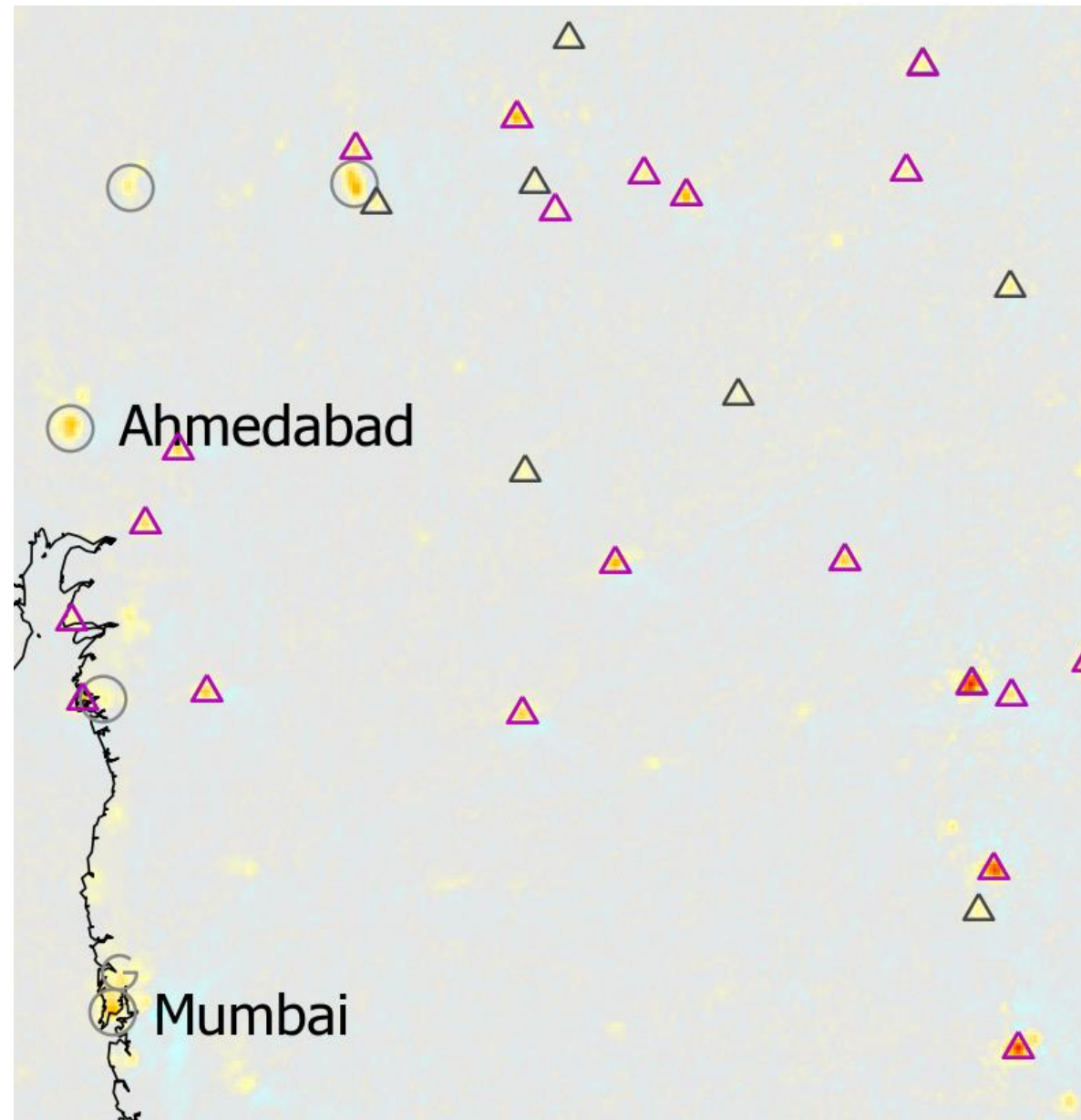
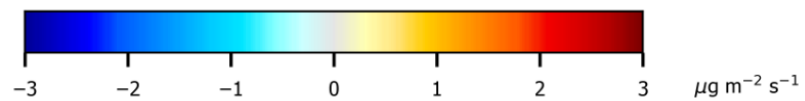
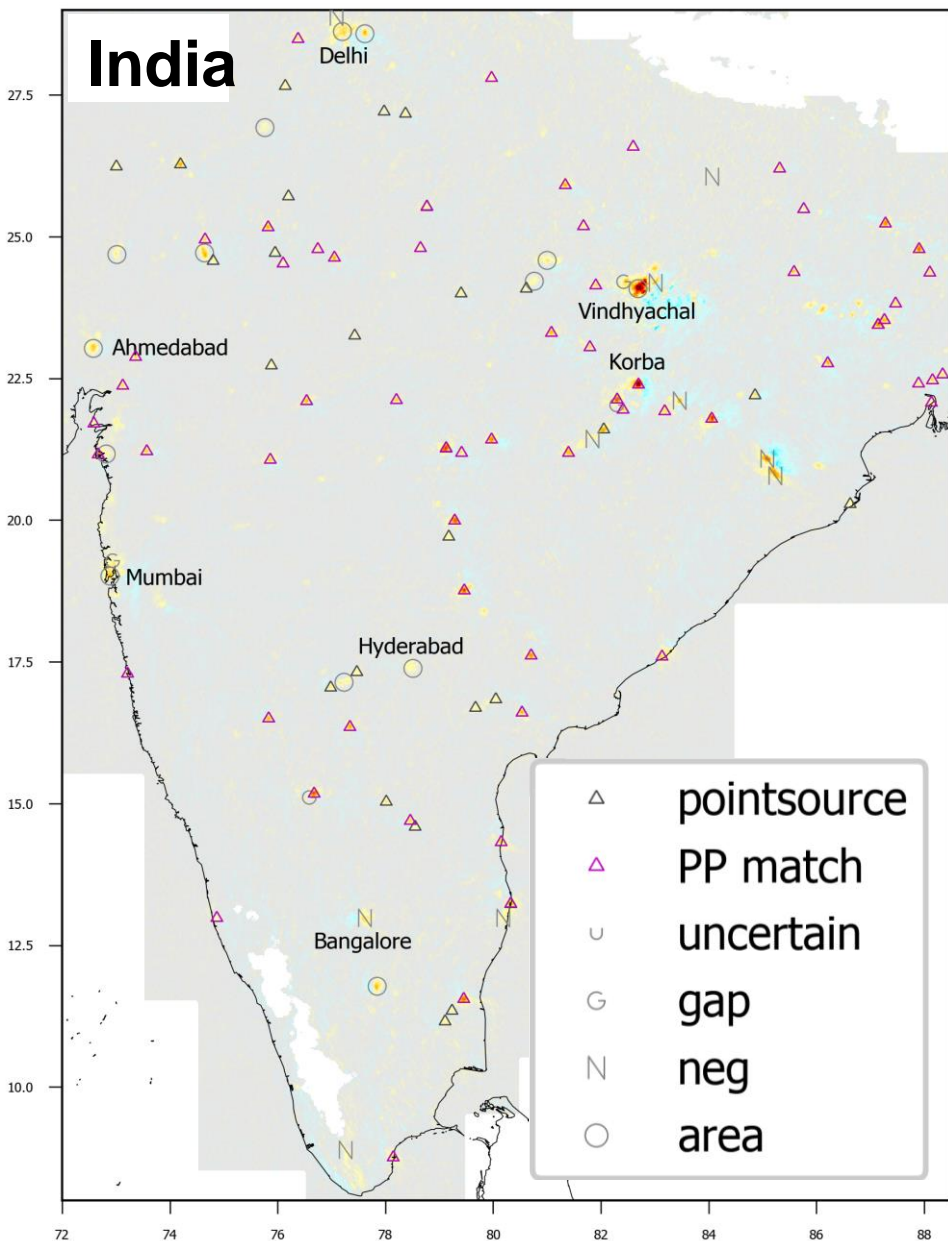


- Point source candidate: maximum of D
- Classify artifacts and ambiguous cases:

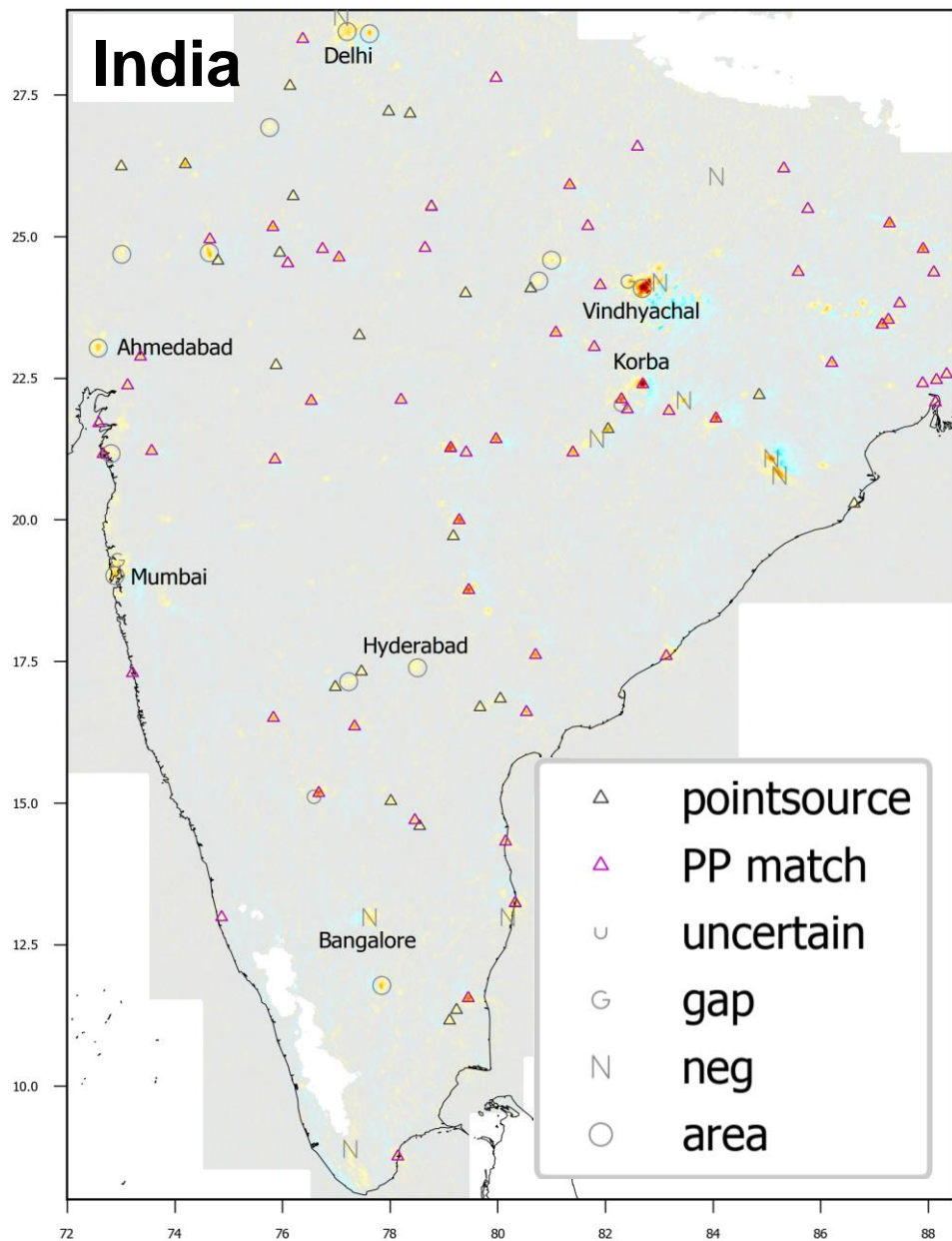


- Fit 2D Gaussian to remaining candidates
- If fit succeeds: add candidate to catalog
- Add GPPD entries within 5 km
- Remove candidate from divergence map

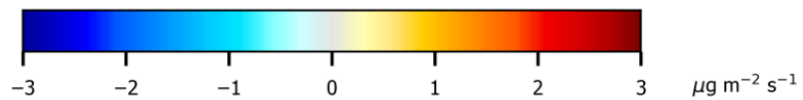
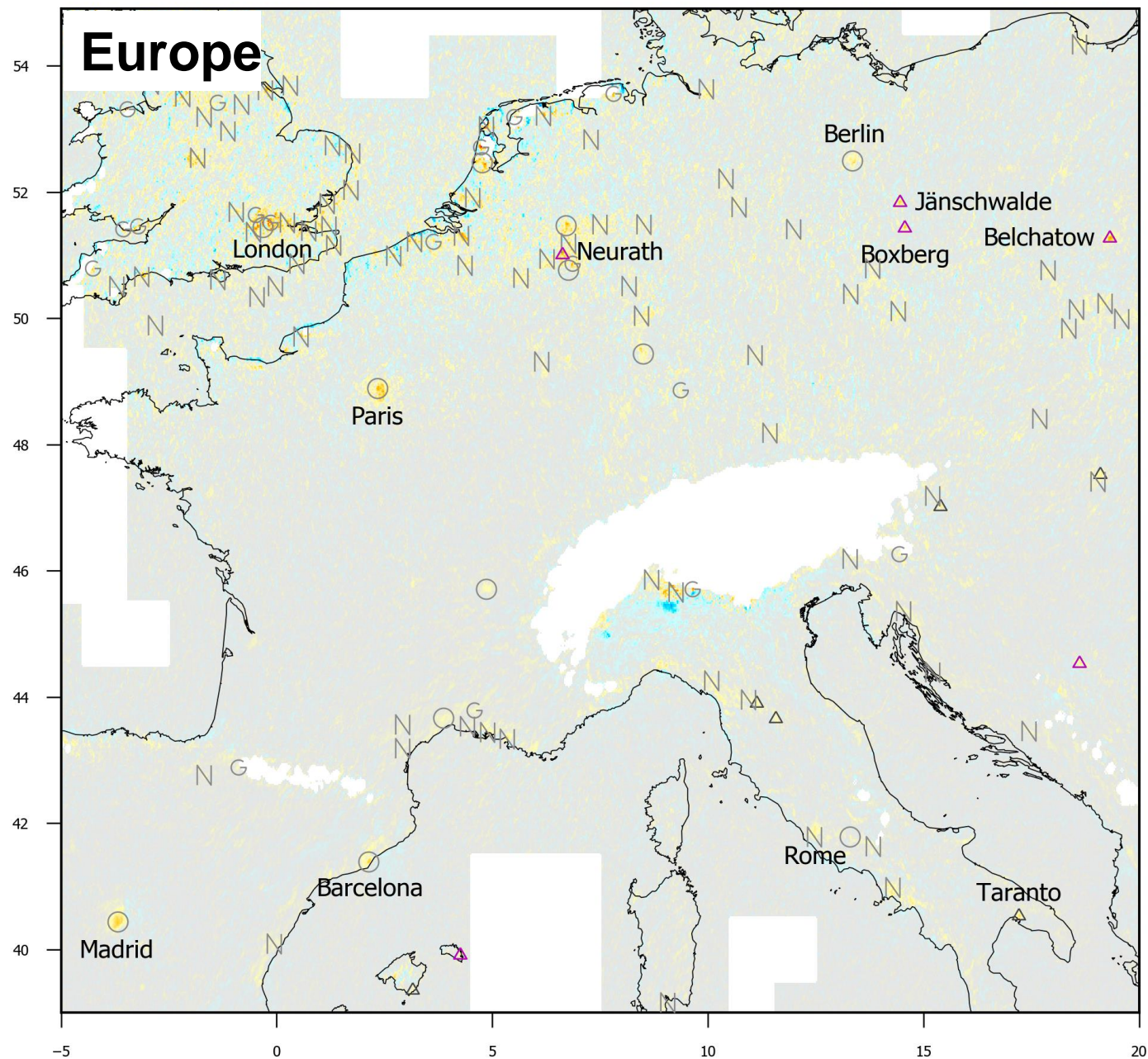
India



India



Europe



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- Catalog lists NO_x point sources worldwide
- High accuracy of point source location
- Catalog is incomplete:
 - Persistent gaps in input data
 - Noise in divergence
 - Systematic artefacts (input wind fields / mountains)
- Emissions are biased low
- Possible reasons:
 - Lifetime correction
 - NO_x/NO₂ ratio
 - A-priori profile / averaging kernel (AK)

Catalog of NO_x emissions from point sources as derived from the divergence of the NO₂ flux for TROPOMI

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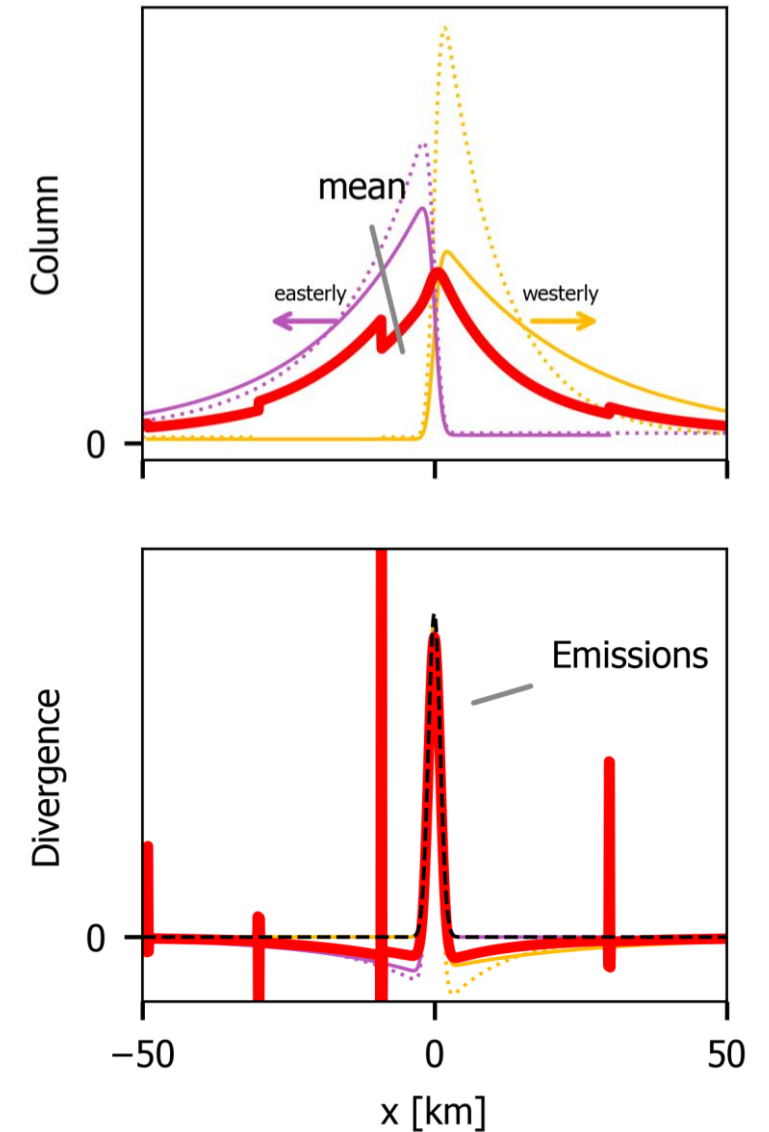
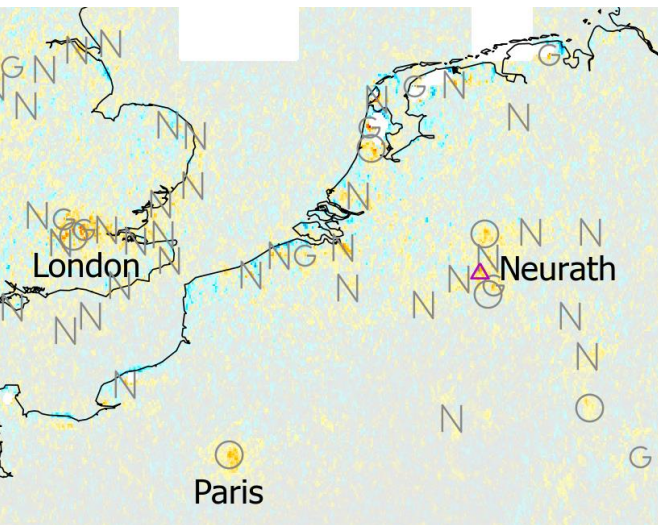
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Noise in divergence

- Gaps due to cloud masking cause „jumps“ in mean VCD & mean flux
- Divergence (spatial derivative) results in spikes
- Effect stronger for
 - frequent cloud occurrence
 - polluted background
- Poor performance over e.g. Western Europe or China
- Longer time periods needed



- For quantification of NO_x emissions, information on the NO_x/NO₂ ratio is needed.
- In Beirle et al., 2019: constant (1.32)
- In Beirle et al., 2021: calculated for each TROPOMI pixel (1.35±0.08) (using $J = f(\text{SZA})$ and [O₃] from model climatology)
- Cloud free conditions around noon, SZA < 65°
- In-plume NO_x/NO₂ ratio might be considerably higher (Ozone titration)
- In this case, the divergence method will „notice“ the NO_x source as soon as the NO is converted to NO₂, i.e. the peak in D would be shifted downwind
- For quantification of complete plume: „background“ ratio is appropriate
- On TROPOMI spatial resolution, we do not observe such a shift

A-priori vertical profile

- Needed for the calculation of averaging kernels (AKs)
- Generally:
 - complex
 - not represented appropriately by global model on relatively coarse spatial resolution
- VCD can be corrected for actual profile via provided AKs

*Synthetic data
for illustration:*

E: Emissions

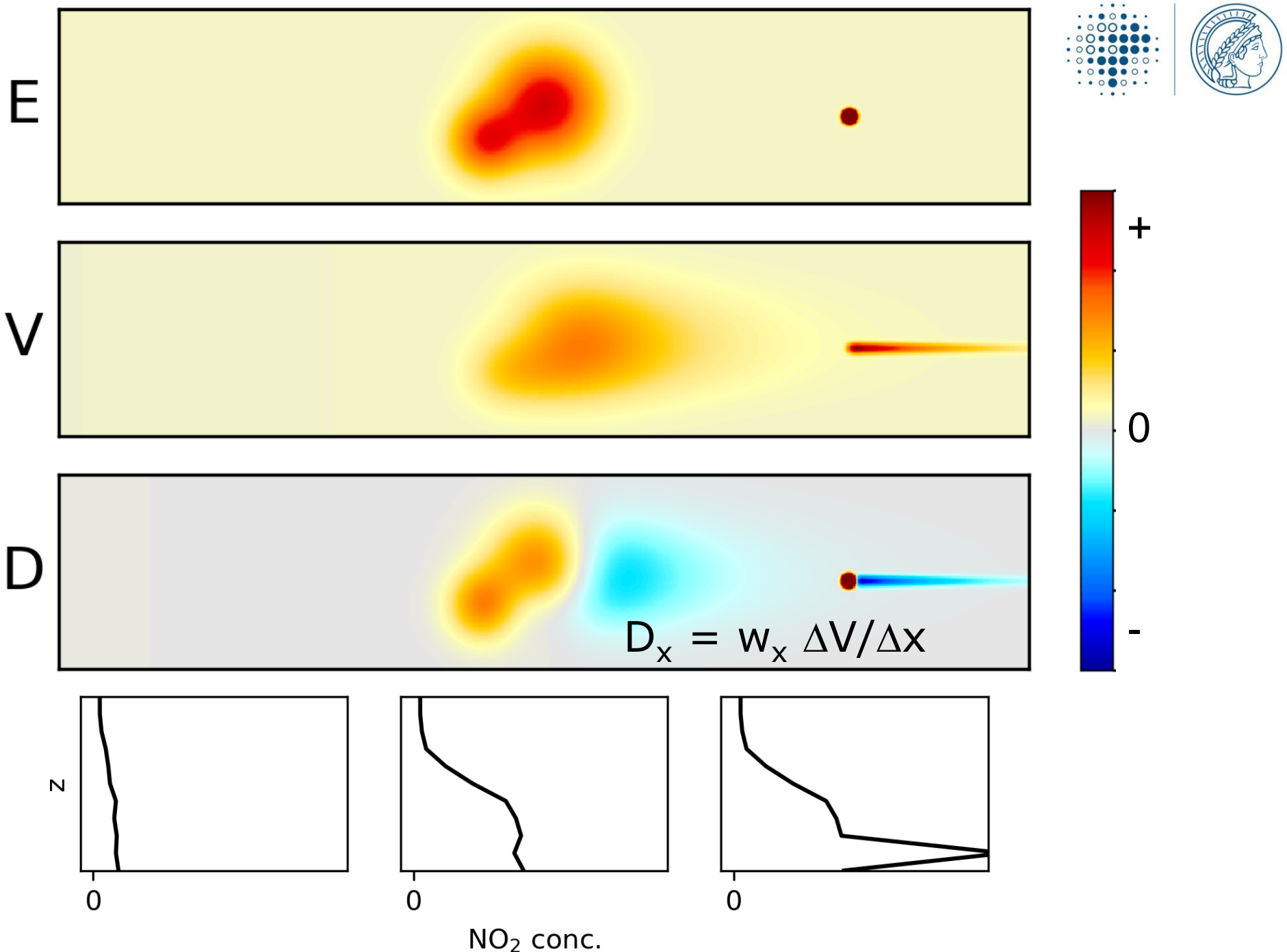
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$\mathbf{w}=(u, v)$: Wind

$\mathbf{F} = \mathbf{w} \cdot \mathbf{V}$: Flux

$D = \nabla \cdot \mathbf{F}$:
Divergence

For correct V:
NO₂ profile required
(complex!)



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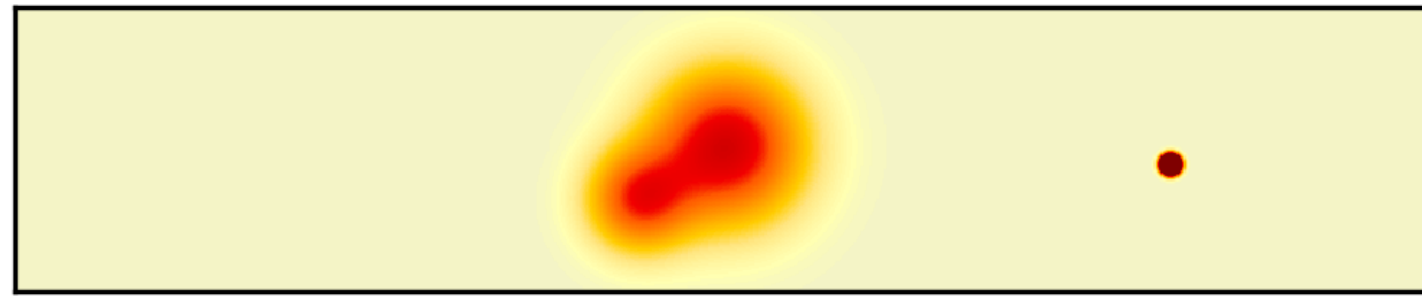
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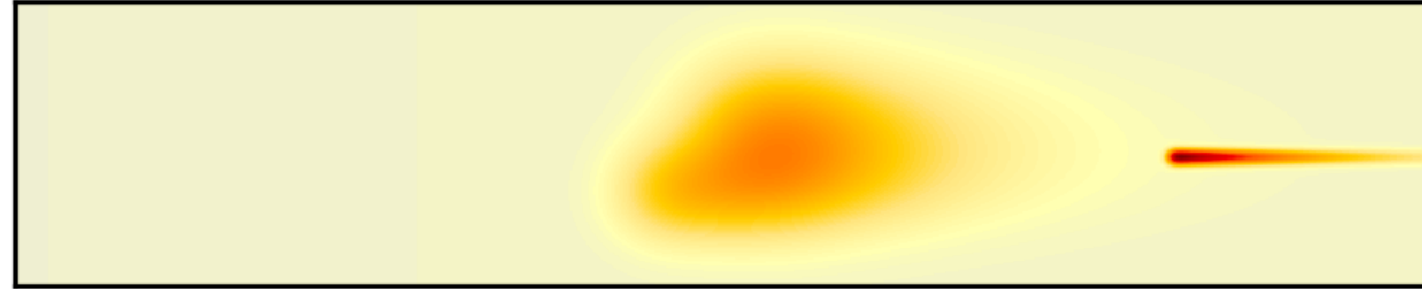
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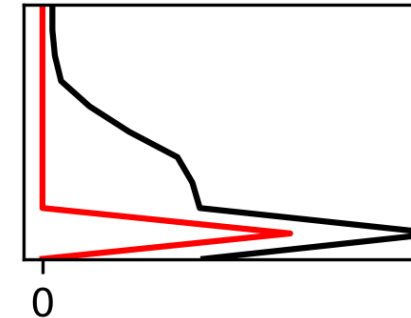
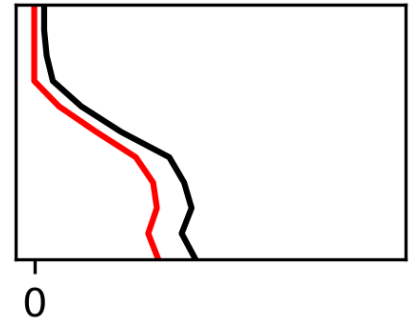
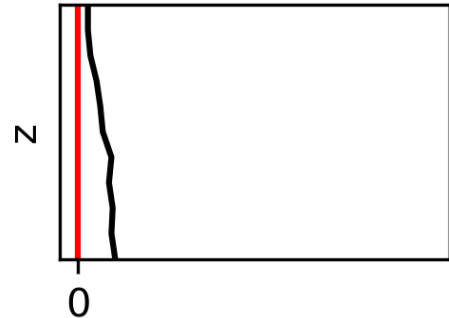
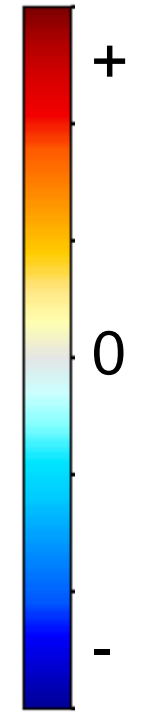
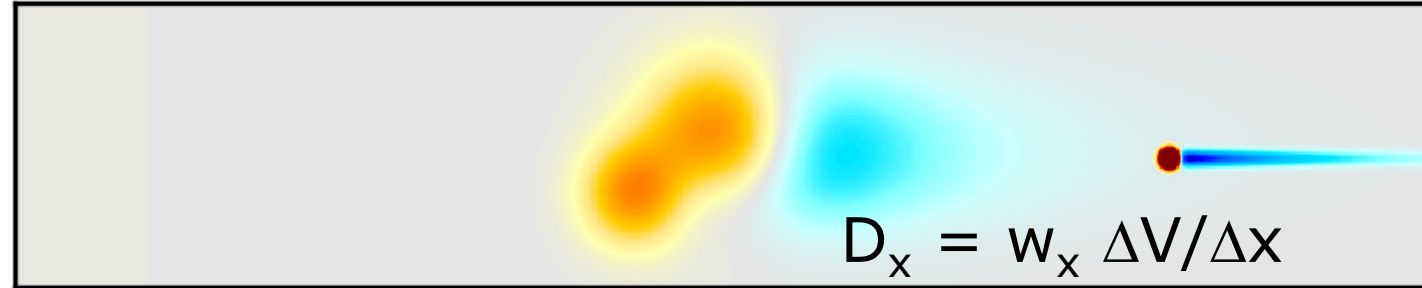
E



V



D



For correct D:
NO₂ excess
profile required
(simple!)

NO₂ conc.

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- Catalog is incomplete:
 - Persistent gaps
 - Noise in divergence
 - Mountains
 - Emissions are biased low:
 - Lifetime correction
 - NO_x/NO₂ ratio
 - A-priori profile / averaging kernel (AK)
- Improved in TROPOMI NO₂ update
 - Consider longer time periods
 - Use wind fields with better resolution
 - To be applied
 - „Background” ratio is appropriate
 - Apply AK for stack height (lowest model layer)

Conclusions

- Divergence of NO_2 flux yields balance of NO_x sources and sinks
- Divergence is linear operator: applicable to mean flux
- Method is particularly sensitive for point sources
- Allows very accurate localization of point sources
- Clouds are crucial:
 - a strict cloud masking is necessary for accurate emission estimates
 - cloud gaps increase noise in divergence
- Quantifying emissions: only excess column matters → profile is known!
- Method also applicable to other trace gases: e.g. SO_2
(Jost et al., P2.4, Thursday afternoon)
- Detection of point sources can support CO_2 satellite missions
- High potential for possible future missions like NITROSAT

Supplement

Divergence of the NO₂ flux

- Direct mapping of emissions: $E = D + S$
- Linear operation: can be applied to mean fluxes
- For area sources (cities): lifetime has to be considered
- Strong sensitivity for point sources
- Requirements:
 - VCDs on high spatial resolution with low noise (i.e. TROPOMI)
 - Cloud free conditions
 - Windy conditions
 - Wind fields (at relevant altitude) as input

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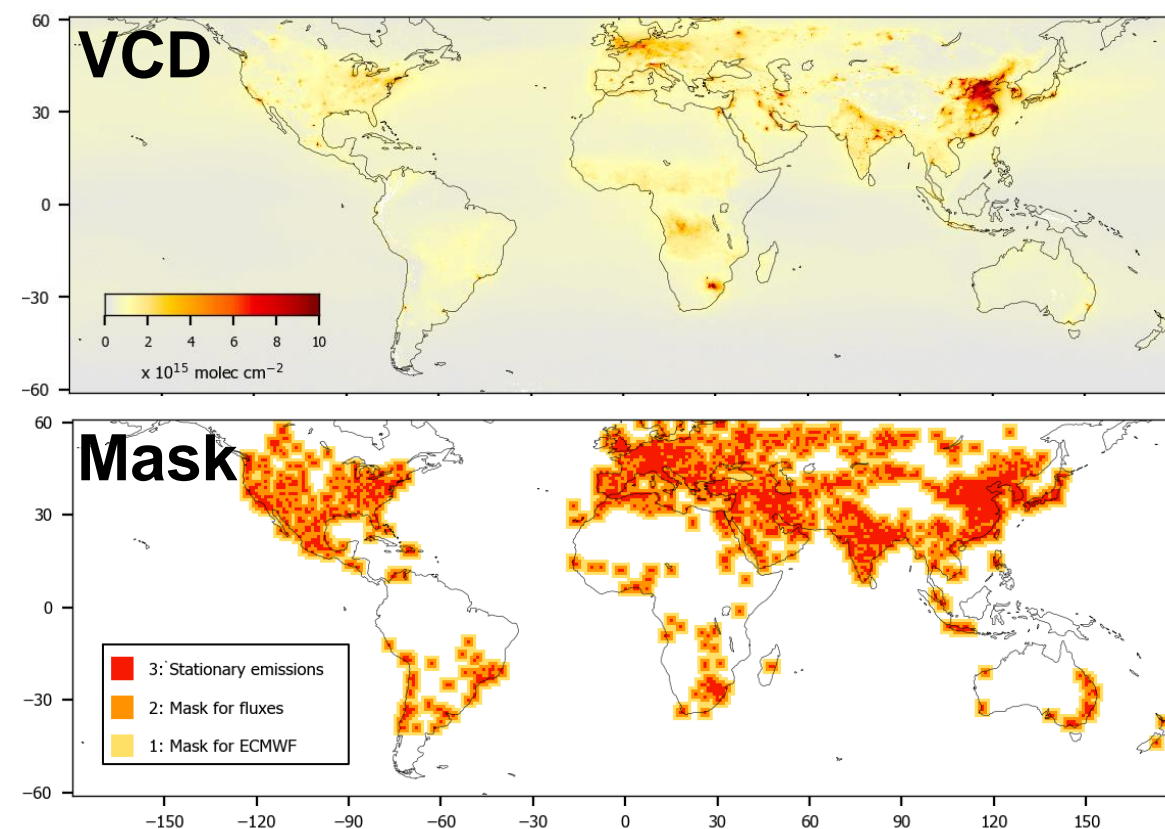


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Method:

- Mask for potential stationary emissions
- Calculate mean fluxes and divergence
- Peak classification and point source emission fit by fully automated algorithm



NO_x/NO₂ ratio

- For quantification of NO_x emissions, information on the NO_x/NO₂ ratio is needed.
- In Beirle et al., 2019: constant (1.32)
- In Beirle et al., 2021: calculated from $J = f(\text{SZA})$ and [O₃] from model climatology
- Only moderate spatial variability:
Cloud free conditions around noon,
SZA < 65°
- In-plume NO_x/NO₂ ratio might be considerably higher (Ozone titration)
- In this case, the divergence method will „notice“ the NO_x source as soon as the NO is converted to NO₂, i.e. the peak in D would be shifted downwind
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